# Frontier Topics in Empirical Economics: Week 2 Non-parametric Method

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- Common Parametric Models Linear Model:  $y = X'\beta + e$ ,  $e \sim N(0, \sigma^2)$ ; Probit/Logit Model:  $P(y|X) = G(X\beta)$  where G is a nonlinear function
- Explicit Parametric Structure for Distribution
- Common Estimator
   OLS, MLE, Nonlinear LS, Efficient GMM etc.
- Key Properties of the Estimator
   Consistency, BLUE, Asymptotic Efficiency etc.

- In linear model, we have to assume that CEF is linear
- Why linear? Simple? Why not  $y = \beta x^{3\gamma} \cdot \ln x + e$ ?
- What if linear specification is wrong?
- Everything collapses. No data can save.
- It becomes only a linear approximation
- For example, if true model is Logit, but not linear regression
- Functional form can be wrong

- Parametric statistics are based on assumptions about the distribution of population from which the sample was taken
- Non-parametric statistics are NOT based on functional form assumptions
- The data can be collected from a sample that does not follow a specific distribution

- Potential Outcome Framework is intrinsically non-parametric
- If we can directly get estimations of E[y|x=1] and E[y|x=0]
- We can estimate the ATE/ATT in a more general way without regression
- There are many other statistical modeling methods
- Non-parametric, semi-parametric to estimate CEF directly
- To understand tools beyond linear regression

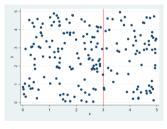
- Let's forget about the model functional form
- Give up the "parametric" model like linear regression
- Do not assume that CEF is linear
- Go back to the original question to estimate  $E(y_i|x_i)$  without imposing any functional form assumption

- Notation:  $x_i, y_i$  denotes random variable;  $X_i, Y_i$  denotes realizations; x, y denotes random variables or some value of the random variables
- Realizations are given (sample), they are NOT random in our context  $\int x \sum_{i=1}^{n} X_{i} dx = \sum_{i=1}^{n} X_{i} \int x dx$

- Let's consider the first non-parametric method: Kernel regression
- It is super intuitive and interesting
- Instead of assuming  $E(y_i|x_i) = x_i'\beta$ , we consider this CEF point by point
- That is, estimate  $E(y_i|x_i)$  for each possible point of  $x_i = x$

#### Step 1: Estimating a cumulative density

Consider estimating a cumulative density function (CDF)



- What is the CDF at x = 3?  $\hat{F}(x = 3) =$ ?
- Go back to kindergarten!

Just count how many points lie on the left to the red line:

$$\hat{F}(x=3) = \frac{1}{n} \sum \mathbf{1}(X_i \le 3)$$

■ In general, we have an estimation of F(x) as:

$$F(x) = P(X \le x) \Rightarrow \hat{F}(x) = \frac{1}{n} \sum_{i=1}^{n} \mathbf{1}(X_i \le x)$$

lacktriangle The proportion of points (realizations) that are smaller than x

#### Step 2: Estimating a probability density

- Consider estimating a probability density function (PDF)
- PDF represents a marginal increase in CDF at some point (derivative)

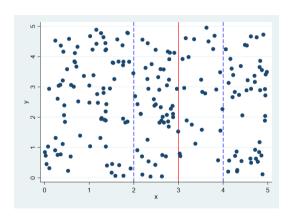
$$f(x) = \frac{dF(x)}{dx} = \lim_{h \to 0} \frac{F(x+h) - F(x-h)}{2h}$$
$$\hat{f}(x) = \frac{\hat{F}(x+h) - \hat{F}(x-h)}{2h}$$

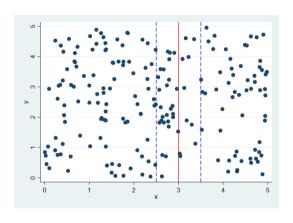
- Changes of F(x) in a very small interval (with length 2h)
- h is called "bandwidth"

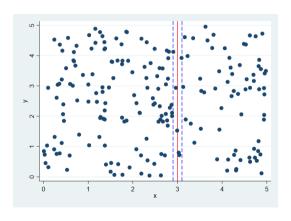
■ Then we can write the probability density f(x) at some value x as:

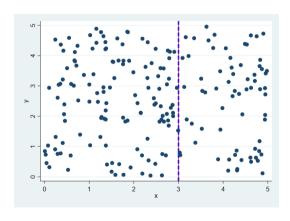
$$\hat{f}(x) = \frac{1}{2h} \left[ \frac{1}{n} \sum_{i=1}^{n} \mathbf{1}(X_i \le x + h) - \frac{1}{n} \sum_{i=1}^{n} \mathbf{1}(X_i \le x - h) \right]$$
$$= \frac{1}{n} \sum_{i=1}^{n} \frac{1}{2h} \mathbf{1}(x - h \le X_i \le x + h)$$

- How to interpret this?
- We count the number of obs within a small interval around x, dividing by the length and the total number of obs
- $\sum_{i=1}^{n} \frac{1}{2h} \mathbf{1}(x h \le X_i \le x + h)$  is the number of obs per unit length
- When n is large, we can choose very small h









■ Define  $k(v) = \frac{1}{2}\mathbf{1}(|v| \le 1)$ . Then we have:

$$\hat{f}(x) = \frac{1}{n} \sum_{i=1}^{n} \frac{1}{h} k \left( \frac{X_i - x}{h} \right)$$

- We call k(v) a uniform kernel function
- This  $\hat{f}(x)$  is a kernel estimator of the PDF (uniform kernel)
- Kernel is weight!
- There can be other kinds of kernel functions, when we assign different weights to different observations

- A function can be used as a kernel if
  - k(v) is integrated to 1
  - k(v) is symmetric with k(v) = k(-v)
- The weights sum to one; The weights are symmetric
- Triangular Kernel:  $k(v) = (1 |v|)\mathbf{1}(|v| \le 1)$
- Epanechnikov Kernel:  $k(v) = \frac{3}{4}(1 v^2)\mathbf{1}(|v| \le 1)$
- Gaussian Kernel:  $k(v) = \frac{1}{2\pi}e^{\frac{-v^2}{2}}$
- Usually, Epanechnikov Kernel and Triangular Kernel are preferred

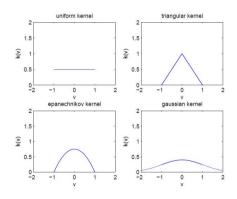


Figure 1: Various Kernels

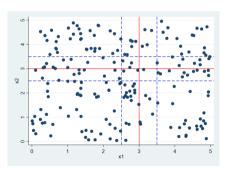
- For multivariate case, let  $v = (v_1, v_2, \dots, v_q)$ .
- Define product kernel:  $K(v) = k(v_1)k(v_2)\cdots, k(v_q)$ .
- The estimator becomes:

$$\hat{f}(x) = \frac{1}{nh_1h_2\cdots h_q} \sum_i K(\frac{X_i - x}{h})$$

- Define  $h = (h_1, h_2, \dots, h_q)$
- $K(\frac{X_i-x}{h})$  is the weighted sum of points within the q-dimension hypercube
- $h_1h_2\cdots h_q$  is the volumn of this q-dimension hypercube

In two dimension case, we have

- $K(\frac{X_i-x}{h})$  is the weighted sum of points within the rectangular
- $h_1 h_2 \cdots h_q$  is the area of this rectangular



#### Step 3: Estimating a CEF

- Finally, let's see how to estimate a CEF using kernel method
- Not like linear regression, we estimate the CEF point by point
- Assume that we have CEF:

$$Y = g(X) + u$$
$$E[Y|X] = g(X)$$

• u has a conditional variance  $Var(u|X) = \sigma^2(x)$ 

#### Step 3: Estimating a CEF

Based on the CDF and PDF we've got, we have Nadaraya-Watson Estimator (N-W) for CEF as follows:

$$\hat{g}(x) = \sum_{i=1}^{n} Y_i K_h(X_i - x), \quad \text{where} \quad K_h(X_i - x) = \frac{K(\frac{X_i - x}{h})}{\sum_{i=1}^{n} K(\frac{X_i - x}{h})}$$

- Intuition: The conditional Expectation of Y given X=x is estimated as a weighted average of observed  $Y_i$  closely around x (within the range of bandwidth h).
- Weights are determined by the kernel function

#### Homework:

- 1. Derive NW Estimator from the kernel estimator of CDF and PDF. This can be a little bit hard. You can refer to Notes from Carol (or Hansen's book) for help.
- 2. What is NW Estimator, if we use the uniform kernel?

• We have g(x) = E(Y|X) as CEF and f(x) as density for x

#### Theorem (Asymptotics for N-W Estimator)

Under some regularity conditions, as  $n \to \infty, h_s \to 0$  (s = 1, ..., q),  $nh_1 ... h_q \to \infty$  and  $nh_1 ... h_q \sum_{s=1}^q h_s^6 \to 0$ , we have:

$$\sqrt{nh_1...h_q}(\hat{g}(x) - g(x) - \sum_{s=1}^q h_s^2 B_s(x)) \stackrel{d}{\to} N(0, \frac{\sigma^2(x)}{f(x)} (\int k(v)^2 dv)^q)$$

where 
$$B_s(x) = \frac{\int v^2 k(v) dv}{2f(x)} \left[ 2 \frac{\partial f(x)}{\partial x_s} \frac{\partial g(x)}{\partial x_s} + f(x) \frac{\partial^2 g(x)}{\partial x_s^2} \right]$$

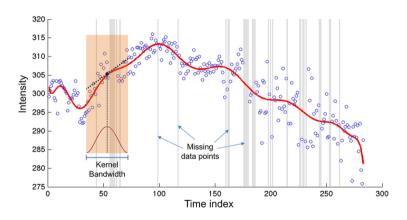
Asymptotic Bias= 
$$\sum_{s=1}^{q} h_s^2 \frac{\int v^2 k(v) dv}{2f(x)} \left[ 2 \frac{\partial f(x)}{\partial x_s} \frac{\partial g(x)}{\partial x_s} + f(x) \frac{\partial^2 g(x)}{\partial x_s^2} \right]$$
 Asymptotic Variance= 
$$\frac{1}{nh_1...h_q} \frac{\sigma^2(x)}{f(x)} \left( \int k(v)^2 dv \right)^q$$

- (1) h<sub>s</sub> ↑⇒ Bias ↑, Variance ↓
   ∴ we have trade-off in choosing kernel bandwidth.
- (2) q ↑⇒ Variance ↑ exponentially We call this "Curse of Dimensionality".
- (3) Kernel more concentrated  $\Rightarrow$  Bias  $\downarrow (\int v^2 k(v) dv)$ , Variance  $\uparrow (\int k(v)^2 dv)$ )
- (4) Slope Effect and Curvature Effect on bias:  $\frac{\partial f(x)}{\partial x_s} \frac{\partial g(x)}{\partial x_s}, \frac{\partial^2 g(x)}{\partial x_s^2}$
- (5)  $f(x) \uparrow \Rightarrow Bias \downarrow$ , Variance  $\downarrow$  (more observations)

### Non-parametric Method: Local Polynomial

- Another widely used kernel-based method is local polynomial
- In linear regression, we use a global linear function to fit data
- In local polynomial, we use piece-wise polynomial (linear) function to fit data interval by interval

### Non-parametric Method: Local Polynomial



For some X = x, we fit g(x) by choosing samples very close to x. Then we fit a polynomial for these observations. (Here, linear)

### Non-parametric Method: Local Polynomial

■ For g(x), we solve the following optimization problem at each point x:

$$\min_{b_0,b_1,\dots,b_p} \sum_{i=1}^n k(\frac{X_i-x}{h})(Y_i-b_0-b_1(X_i-x)-b_2(X_i-x)^2-\dots-b_p(X_i-x)^p)^2$$

- When p = 1, we call it local linear regression
- When p = 2, we call it local quadratic regression

- Both kernel and local polynomial regressions are Kernel-based methods
- There are three disadvantages of this method:
  - Computational burden is large (point by point estimation)
  - Hard to include information or restriction over functional form
  - Requirement of large sample
- Series-based methods alleviate these problems

As usual, we have a CEF model:

$$Y = g(X) + u$$
$$g(X) = E(Y|X)$$

■ We expand the CEF by Taylor Series at zero:

$$g(X) = \sum_{k=0}^{\infty} \frac{g^{(k)}(0)}{k!} X^k$$

■ This infinite series can be approximated by a K-order global polynomial:

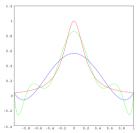
$$g(X) = \sum_{k=0}^{K} \beta_k p_k(X)$$

$$p_0(x) = 1, p_1(x) = x, p_2(x) = x^2, ..., p_K(x) = x^K$$

- We can use OLS to estimate this polynomial
- The vector of  $\{p_0, p_1, p_2, ..., p_K\}$  is called "basis"
- This is "global" polynomial, in contrast to "local" polynomial

- Polynomial is the simplest choice of basis
- In multivariate case (2 variables), it becomes:  $\{1, x_1, x_2, x_1x_2, x_1^2, x_2^2, x_1x_2^2, x_1^2x_2, x_1^2x_2^2...\}$
- Polynomial series has several problems
- It is very sensitive to outliers
- The biggest problem for polynomial series is Runge's phenomenon

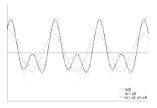
- Runge's phenomenon
- Red: original true function; Blue: fifth-order poly; Green: ninth-order poly



- Since the power polynomials are forced to vary somewhere
- It may be pushed to the boundary
- The boundary part is approximated very poorly

- How to choose the optimal order?
- We will discuss this problem in details in the next lecture when considering model selection and machine learning
- But in general, high order polynomial behaves very bad
- Some other basis are better

■ Fourier basis, derived by Fourier expansion



- Excellent for approximating periodic functions
- Better than poly, but still not good at boundary/jumping point (Gibbs' phenomenon)

### Non-parametric Method: Series-based Methods

- Better than poly, but still not good at boundary/jumping point (Gibbs' phenomenon)
- Let's see an approximation of Fourier series to the square wave



## Non-parametric Method: Series-based Methods

- There are more basis
- Such as Spline basis and Wavelet basis
- They are complicated, rarely seen in Applied works
- But Carol claims that Spline basis is in general a better choice
- If interested, you can read her notes

- Non-parametric model is so general that we do not impose any structure
- Totally data driven, no prior information
- Convergence rate is low, variance is high, requirement for data is high
- What if we want to impose some structure, but not the full structure?
- Semi-parametric model

- Partially linear model
- One of the most popular semi-parametric models

$$Y = X'\beta + g(Z) + u$$
,  $E(u|X,Z) = 0$ ,  $Var(u|X,Z) = \sigma^2$ 

X enters in the model linearly, Z non-parametrically

- **E**stimation of  $\beta$  is simple, we follow Robinson (1988)
- In the first step, conditional on Z and then take the subtract:

$$E(Y|Z) = E(X'|Z)\beta + g(Z)$$
$$Y - E(Y|Z) = [X - E(X|Z)]'\beta + u$$

- E(Y|Z) and E(X|Z) can be estimated using methods introduced previously
- Then we have estimators for Y E(Y|Z) and X E(X|Z)
- Then we can estimate  $\beta$  using OLS
- Asymptotics of this estimator is complicated

■ In the second step, we subtract  $X'\beta$  from Y:

$$Y - X'\beta = g(Z) + u$$

ullet g(Z) can be estimated using methods introduced previously

- Question: How to estimate the variance of  $\hat{g}(Z)$ ?
- Can we use the variance from the non-parametric regression directly?
- No! Because  $Y X'\beta$  is also estimated
- It contains more uncertainty from the first step
- This is a common mistake in empirical work: When you have first stage estimation as known parameter in the second stage, watch out for the std err estimation!

- Similarly, how to conduct inference for first step  $\beta$ ?
- It is a combination of non-parametric and regression estimations
- No closed-form variance equation is available
- Not possible to directly calculate the standard error

In these two cases, we need bootstrap for inference

## Non-parametric Method: Bootstrap

- Bootstrap is a non-parametric method for inference
- It is used when there is no closed-form standard errors
- Instead of deriving the closed-form equation of variance
- We use simulation to estimate it
- Random sampling with replacement

## Non-parametric Method: Bootstrap

- Step 1: Given full sample with size n, draw R new samples of size n, with replacement. Index each new sample by r
- Step 2: Calculate the simulated variance of  $\hat{g}(x)$  by:  $\hat{V}(x) = \frac{1}{R-1} \sum_{r=1}^{R} [\hat{g}_r(x) \hat{g}(x)]^2$
- Step 3: Use  $\hat{V}(x)$  to calculate confidence intervals and implement statistical tests
- We call this bootstrapped variance

## Non-parametric Method: Bootstrap

- But using bootstrapped variance to construct confidence interval is a poor choice
- It relies on asymptotic normality, which is not accurate in finite sample
- A better chioce is "percentile interval"
- ullet First, we stack the sample of bootstrap estimates  $\{\hat{eta}^1,\hat{eta}^2,...,\hat{eta}^R\}$
- We have an empirical distribution of  $\hat{\beta}^r$
- The bootstrap  $100(1-\alpha)\%$  confidence interval is then:  $[q_{\alpha/2}^*, q_{1-\alpha/2}^*]$
- q\* is the quantile of this empirical distribution

## Non-parametric Method: Application

- Where to apply non-parametric methods?
- Anything related to estimation of CEF
- Potential outcome framework is non-parametric
- Non-parametric inference in complicated models (Bootstrap)
- If you focus on prediction and fit, but not the structure behind it Predict stock price, machine learning, RDD fitting
- We will show these in the following lectures

#### **Final Conclusion**

- There are statistical modeling methods other than Linear regression
- Non-parametric methods impose no prior structure, totally data-driven
  - Kernel-based methods: N-W estimator, Local polynomial
  - Series-based methods: Polynomial, Fourier, Spline, Wavelet
- They are very useful in causal inference to directly estimate CEF
- However, they have weaknesses: Not always better to make model more flexible
  - Hard to incorporate restrictions
  - Require large sample size to have accurate estimation
- We will discuss more about it next week
- A semi-parametric model is between non-parametric and parametric

#### References

Robinson, Peter M. 1988. "Root-N-consistent Semiparametric Regression." Econometrica: 931–954.